

# Four-vector deformations and holographic principle

work based on works

[2302.08749, 2011.11424]

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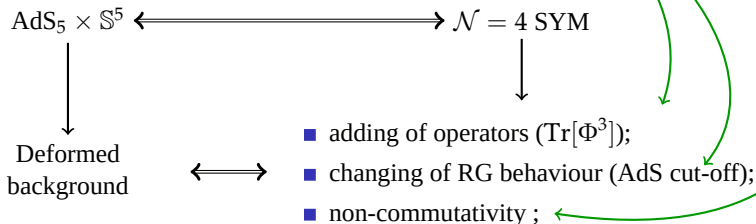
# Holographic interpretation

Bivector transformation - hidden symmetry of solutions space of 10d supergravity

$$(G + B)^{-1} = (g + b)^{-1} + \beta, \quad (1)$$

$$\beta^{mn} = k_a^m k_b^n \mathbf{r}^{ab}$$

Backgrounds looks like  $\text{AdS}_D \times M_{10-D}$ : duals to CFT deformations



# Holographic interpretation

- There are three possibilities:
  - 1 All isometries were taken through M: **marginal deformations**;
  - 2 All isometries were taken through AdS: non-commutativity;
  - 3 Mixed case: dipole deformations.
- In case of using of basic hidden symmetry of space of solutions of supergravity, isometries of  $M_{10-D}$  must to be commutative, thus acceptable only **abelian** deformations

$$[k_a, k_b] = 0$$

- U-duality (in following **advanced**) **hidden symmetry of supergravity**, allow us expand acceptable view of deformation
- Advanced hidden symmetry **allow non-abelian isometries** of compact space  $M_{10-D}$

$$[k_a, k_b] = f_{ab}{}^c k_c$$

# Non-abelian deformations

- YB bi-vector transformation of vary solution with b-field  
[Bakhmatov, Colgain, Sheikh-Jabbari, Yavatanoo (2018)]

$$(G + B)^{-1} = (g + b)^{-1} + \beta \quad (2)$$

- Necessary to define

$$\begin{aligned} [k_a, k_b] &= f_{ab}{}^c k_c && \text{(algebra of symmetries)} \\ \beta^{mn} &= k_a{}^m k_b{}^n r^{ab} && \text{(bi-vector ansatz);} \\ r^{b_1[a_1} r^{b_2|a_2} f_{b_1 b_2}{}^{a_3]} &= 0 && \text{(classical YB equation);} \\ r^{b_1 b_2} f_{b_1 b_2}{}^a k_a{}^m &= I^m = 0 && \text{(unimodularity);} \end{aligned} \quad (3)$$

In case of **compact** isometrics:

- Abelian  $u(1)^n$ :  $f_{ab}{}^c = 0 \implies \forall r_{ab}$
- Non-abelian  $(SU(N), SO(N), \dots)$ :  $r_{ab} \equiv 0$   
[Lichnerowicz, Medina (1988), Pop, Stolin (2007)]

# Deformation of $M_5 \times N_5$ solutions of IIB

Consider solution in view  $M_5 \times N_5$  with

$$\begin{aligned}
 ds^2 &= \underbrace{g_{\mu\nu} dx^\mu dx^\nu}_{AdS_5} + \underbrace{g_{mn} dy^m dy^n}_{S^5}, \\
 C_{S^5} &= \frac{1}{4!} C_{mnlk}(y) dy^m \wedge dy^n \wedge dy^k \wedge dy^l, \\
 C_{AdS_5} &= \frac{1}{4!} c_{\mu\nu\kappa\lambda}(x) dx^\mu \wedge dx^\nu \wedge dx^\kappa \wedge dx^\lambda
 \end{aligned} \tag{4}$$

- Solution  $AdS_5 \times S^5$  corresponds to ansatz and dual to  $\mathcal{N} = 4, D = 4$  SYM

## Four-vector deformation

Four-vector transformation of IIB supergravity fields in clear view:

$$\begin{aligned}
 \mathbf{K} &= (1 + \mathbf{W})^2 \pm \mathbf{W}^2 \\
 \mathbf{m}'^{\alpha\beta} &= \mathbf{m}^{\alpha\beta} \\
 \mathbf{G}'_{\mu\nu} &= \mathbf{K}^{\frac{1}{2}} \mathbf{G}_{\mu\nu} \\
 \prime^m &= \mathbf{K}^{-\frac{1}{4}} \mathbf{m} (1 + \mathbf{W}) \pm \mathbf{K}^{-\frac{1}{4}} \mathbf{W}^m \\
 \mathbf{g}'_{mn} &= \mathbf{K}^{-\frac{1}{2}} (\mathbf{g}_{mn} + 2 \mathbf{W}_{(mn)} \pm (1 \pm^2) \mathbf{W}_m \mathbf{W}_n), \\
 \mathbf{W}_m &= \frac{1}{4!} \epsilon_{mp_1 \dots p_4}^{\mathbf{p}_1 \dots \mathbf{p}_4}, \\
 \mathbf{g}' &= \mathbf{K}^{-\frac{3}{2}} \mathbf{g},
 \end{aligned} \tag{5}$$

where were in bi case:

$$(\mathbf{G} + \mathbf{B})^{-1} = (\mathbf{g} + \mathbf{b})^{-1} + \beta \tag{6}$$

## Generalization of the Yang–Baxter equation in IIB case

- As in case of bi–vector deformation, we can span  $\Omega^{mnl}$  on Killing vectors:

$$\Omega^{mnl} = \rho^{i_1 i_2 i_3 i_4} k_{i_1}^m k_{i_2}^n k_{i_3}^k k_{i_4}^l \quad (7)$$

- Enough conditions on coordinates of four-vector for generation of IIB solution from IIB solution

**Linear conditions:** IIB analogue of unimodularity condition

$$\rho^{[a_1 a_2 | a_3 a_4 | f_{a_3 a_4}^{a_5]} = 0. \quad (8)$$

**Quadratic condition:** Generalization of the classical Yang–Baxter equation in case of four-vector

$$\rho^{[a_1 a_2 | a_3 a_4 | \rho^{a_5 a_6 a_7] a_8} f_{a_3 a_8}^{a_9} - 3 \rho^{[a_1 a_2 | a_3 a_4 | \rho^{a_5 a_6 | a_9 a_8 | f_{a_3 a_8}^{a_7]} = 0. \quad (9)$$

# Results

Four-vector deformation of  $\text{AdS}_5 \times \mathbb{S}^5$  on AdS isometries:

$$K = 1 - \left(\frac{R}{z}\right)^3 \left( \left(\frac{x^a}{z}\right) \rho_a \right) \quad (10)$$

$$ds^2 = K^{-\frac{1}{2}} \left(\frac{R}{z}\right)^2 \left[ -(dx^0)^2 + (dx^1)^2 + (dx^2)^2 + K dz^2 + \frac{1}{2} \left(\frac{R}{z}\right)^3 \rho_a dx^a dz \right] \\ + R^2 K^{\frac{1}{2}} d\Omega_{(5)}^2, \\ F = -\frac{1}{R} \left( -K^{-2} d\text{Vol}(\text{AdS}_5) + d\text{Vol}(\mathbb{S}^5) \right). \quad (11)$$

where  $\rho^a$  must be such, that  $\rho^2 = -(\rho^0)^2 + (\rho^1)^2 + (\rho^2)^2 + (\rho^3)^2 = 0$  for (11) to be IIB supergravity solution.



## Summary and discussion

- For IIB supergravity were found new type of symmetry of space of solutions by four vector, and found conditions on it, built example of four-vector deformation
- In following works try to find full solution of conditions on four-vector on  $\mathbb{S}^5$  isometrics
- Find precisely view of new deformations of  $\text{AdS}_5 \times \mathbb{S}^5$  that will be corresponds to non-supersymmetric conform manifold

Thanks for your attention!

